

## Precise. Compact. Reliable.

# MPG Miniature Parallel Gripper

2-finger parallel gripper with smooth running base jaws guided on roller bearings

### Field of Application

Gripping and moving of small to medium-sized workpieces in low contaminated environments, such as assembly, testing, laboratory, and pharmaceutical industry

### Advantages – Your benefit

**Cross roller guidance** for precise gripping through base jaw guidance with minimum play

**Base jaws guided on double roller bearings** ensuring low friction and smooth running actuation

**Mounting from two sides in three screw directions** for universal and flexible gripper assembly

**Air supply via hose-free direct connection or screw connections** for flexible pressure supply in all automated systems



Sizes  
Quantity: 9



Weight  
0.01 .. 0.7 kg



Gripping force  
7 .. 270 N



Stroke per jaw  
1 .. 10 mm



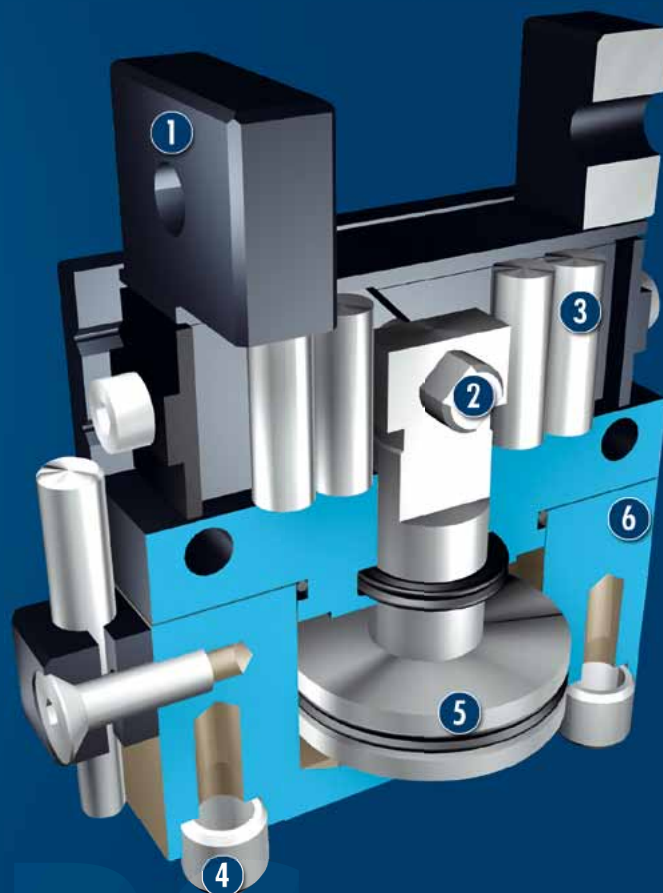
Workpiece weight  
0.05 .. 1.0 kg



## Functional Description

The piston is moved up or down by compressed air. The side hooks at the upper end of the piston rod guide in the angular slots of both base jaws, and thus transform

this movement into the synchronized opening or closing of the base fingers.



- ① **Base jaw**  
for the connection of workpiece-specific gripper fingers
- ② **Wedge-hook design**  
for high power transmission and centric gripping
- ③ **Cross roller guidance**  
Precise gripping through base jaw guide with minimum play
- ④ **Centering and mounting possibilities**  
for assembly of the gripper to a base area and at the long side
- ⑤ **Drive**  
Double-acting piston drive system
- ⑥ **Housing**  
Weight-optimized through application of high-strength aluminum alloy

CAD data, operating manuals and other current product documents are available at [www.schunk.com](http://www.schunk.com)

## General Notes about the Series

**Operating principle:** Wedge-hook kinematics

**Housing material:** Aluminum alloy, anodized

**Cover material:** Steel

**Base jaw material:** Steel

**Actuation:** pneumatic, with filtered compressed air as per DIN ISO 8573-1: 7 4 4

**Warranty:** 24 months (details, general terms and conditions and operating manuals can be downloaded at [www.schunk.com](http://www.schunk.com))

**Scope of delivery:** Mount for proximity switch, centering sleeves, O-rings for direct connection, assembly and operating manual with declaration of incorporation.

**Gripping force maintenance device:** possible with variants with mechanical maintenance of gripping force or SDV-P pressure maintenance valve

**Gripping force:** is the arithmetic total of the gripping force applied to each gripper jaw at distance P (see illustration).

**Finger length:** is measured from the upper edge of the gripper housing in the direction of the main axis. The breach of the max. permitted finger length can bring higher abrasion. The maximum permissible finger length applies up to the nominal operating pressure. With higher pressures, the finger length must be reduced proportionally to the nominal operating pressure.

**Repeat accuracy:** is defined as the spread of the limit position after 100 consecutive strokes.

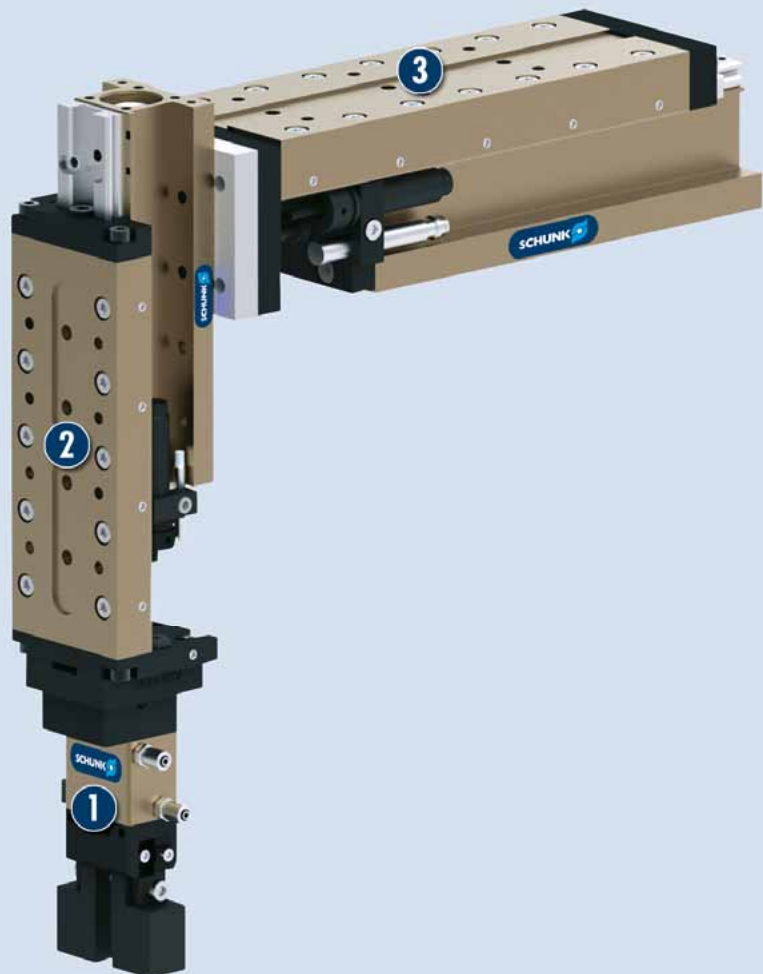
**Workpiece weight:** is calculated for a force-fit connection with a coefficient of friction of 0.1 and a safety factor of 2 against slippage of the workpiece on acceleration due to gravity g. Considerably heavier workpiece weights are permitted with form-fit gripping.

**Closing and opening times:** are purely the times that the base jaws or fingers are in motion. Valve switching times, hose filling times or PLC reaction times are not included in the above times and must be taken into consideration when determining cycle times.

## Application example

Pneumatically driven, two axis assembly machine for small components

- ① MPG 2-Finger Parallel Gripper with standard finger blanks
- ② CLM Mini-slide for vertical movement
- ③ CLM Mini-slide for horizontal movement



## SCHUNK offers more ...

The following components make the product MPG even more productive – the suitable addition for the highest functionality, flexibility, reliability, and controlled production.



Sensor System



Sensor Cables



Sensor Distributor



Flexible Position Sensor



Fittings



SDV-P Pressure Maintenance Valve



Finger Blanks



Switching Valve



Gripper Pads



Carbide Clamping Inserts



Plastic Inserts



Centering Sleeves

① Further information regarding the products can be found on the following product pages or at [www.schunk.com](http://www.schunk.com). Please contact us for further information: SCHUNK technical hotline +49-7133-103-2696

## Options and special Information

**Gripping force maintenance version AS / IS:** The mechanical gripping force maintenance version ensures a minimum gripping force also in the case of a drop in pressure. In the AS / S version this has the effect of a closing force, in the IS version of an opening force.

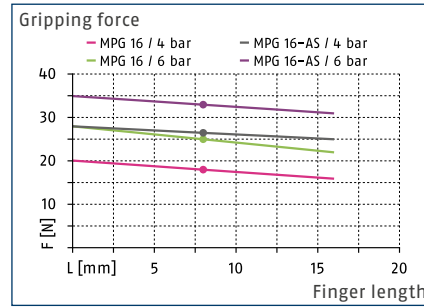
**Additional mounting bores:** for centering the fingers via sleeves, instead of normal mounting surfaces. Special versions on request.

# MPG 16

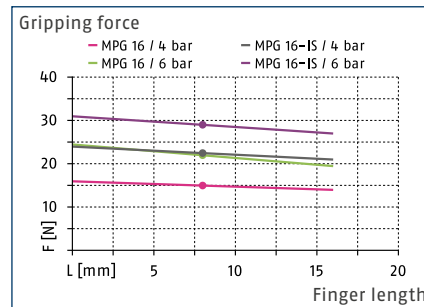
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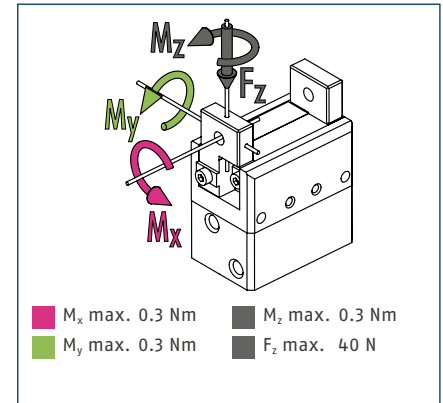
## Gripping force, O.D. gripping



## Gripping force, I.D. gripping



## Finger load

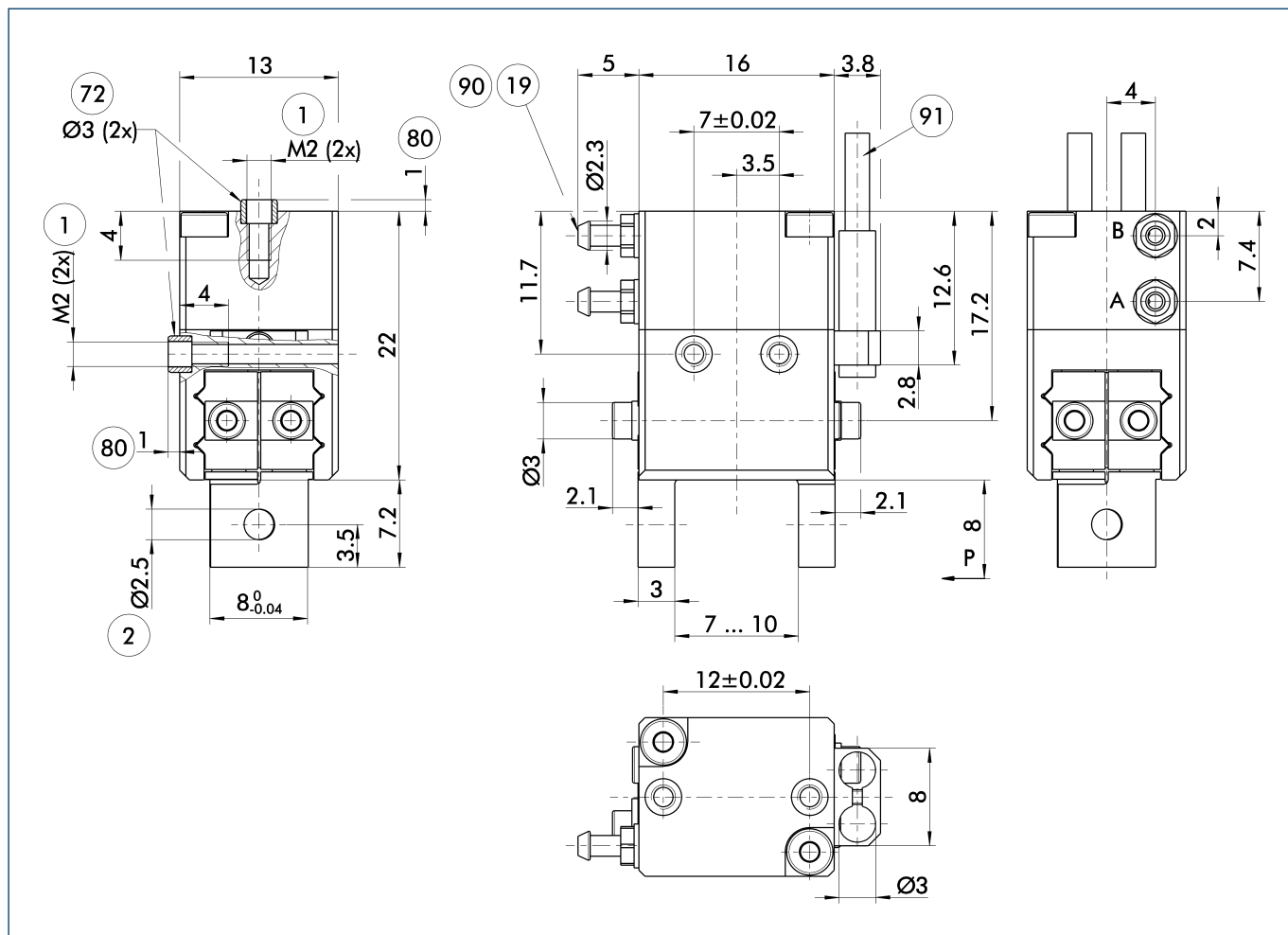


① The indicated moments and forces are static values, apply per base jaw and may occur simultaneously.  $M_y$  may arise in addition to the moment generated by the gripping force itself. If the max. permitted finger weight is exceeded, it is impreative to throttle the air supply so that the jaw movement occurs without any hitting or bouncing. Service life may be reduced.

## Technical data

Description		MPG 16	MPG 16-AS	MPG 16-IS
ID		0340008	0340038	0340058
Stroke per jaw	[mm]	1.5	1.5	1.5
Closing- / opening force	[N]	25/22	33/-	-/29
min. spring force	[N]		8	7
Weight	[kg]	0.03	0.03	0.03
Recommended workpiece weight	[kg]	0.13	0.13	0.13
Fluid consumption per double stroke	[cm <sup>3</sup> ]	0.34	0.64	0.53
min. / max. operating pressure	[bar]	2/8	4/6.5	4/6.5
Nominal operating pressure	[bar]	6	6	6
Closing- / opening time	[s]	0.01/0.01	0.01/0.025	0.025/0.01
Closing- / opening time only with spring	[s]		0.10	0.10
max. permitted finger length	[mm]	16	16	16
max. permitted weight per finger	[kg]	0.01	0.01	0.01
IP class		30	30	30
min. / max. ambient temperature	[°C]	5/90	5/90	5/90
Repeat accuracy	[mm]	0.02	0.02	0.02
Cleanroom class ISO 14644-1		5	5	5

Main view



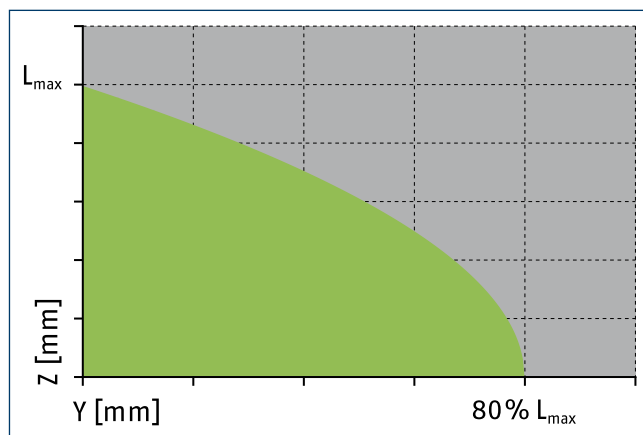
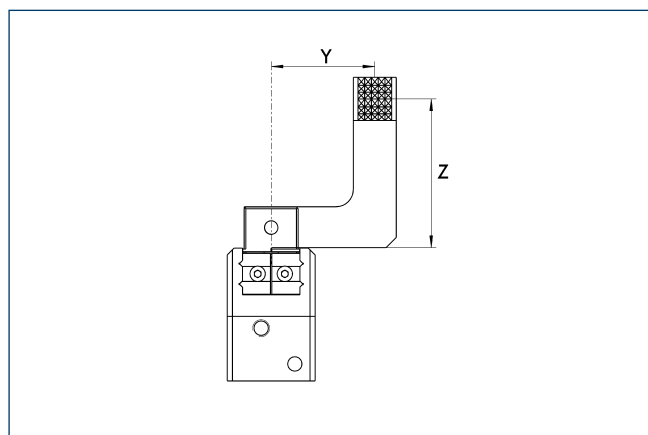
The drawing shows the basic version of the gripper with open jaws, without dimensional consideration of the options described below.

① The SDV-P pressure maintenance valve can also be used for I.D. or O.D. gripping alternatively or in addition to the spring-loaded, mechanical gripping force maintenance device (see catalog section on "Accessories").

- A, a Main / direct connection, gripper opening
- B, b Main / direct connection, gripper closing
- ① Gripper connection
- ② Finger connection
- ⑱ Air connection

- ⑦② Fit for centering sleeves
- ⑧① Depth of the centering sleeve hole in the mating part
- ⑨① Bosch-Rexroth compressed air hose, TU1-S (Ø 3.0 – 0.6) series, Order no.: 1820712066 (-67/-68/-69)
- ⑨① IN ... sensor

Maximum permitted finger projection



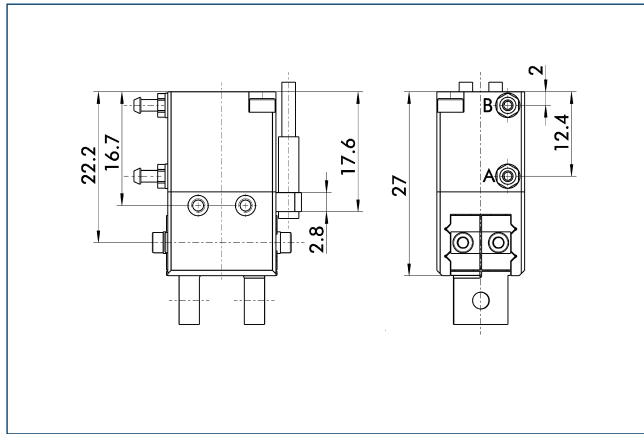
■ Permitted range      ■ Inadmissible range

L<sub>max</sub> is equivalent to the maximum permitted finger length, see the chart of technical specifications.

# MPG 16

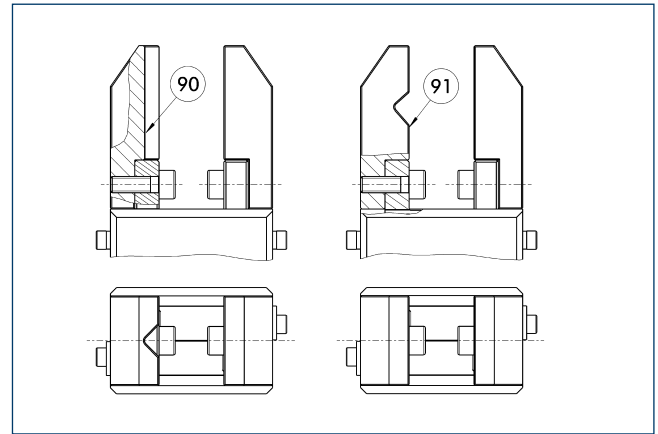
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## Gripping force maintenance device AS / IS



The mechanical maintenance of gripping force also assures a minimum gripping force in the case of a loss of pressure. With the AS / S variant, this acts as a closing force, and as an opening force for the IS variant. The maintenance of gripping force element can also be used as a means for increasing gripping force or for single actuated gripping.

## Jaw design



90 Vertical prism

91 Horizontal prism

A three-point support of the gripped workpiece is beneficial for gripping the workpiece with repeat accuracy and process reliability. More than three support points lead to a redundancy of the system. The drawing shows two alternative recommendations for the jaw design for coaxial and radial gripping of a cylindrical part.



